

Adaptive finite elements with high aspect ratio for the computation of dendritic growth and coalescence in binary alloys.

Marco Picasso

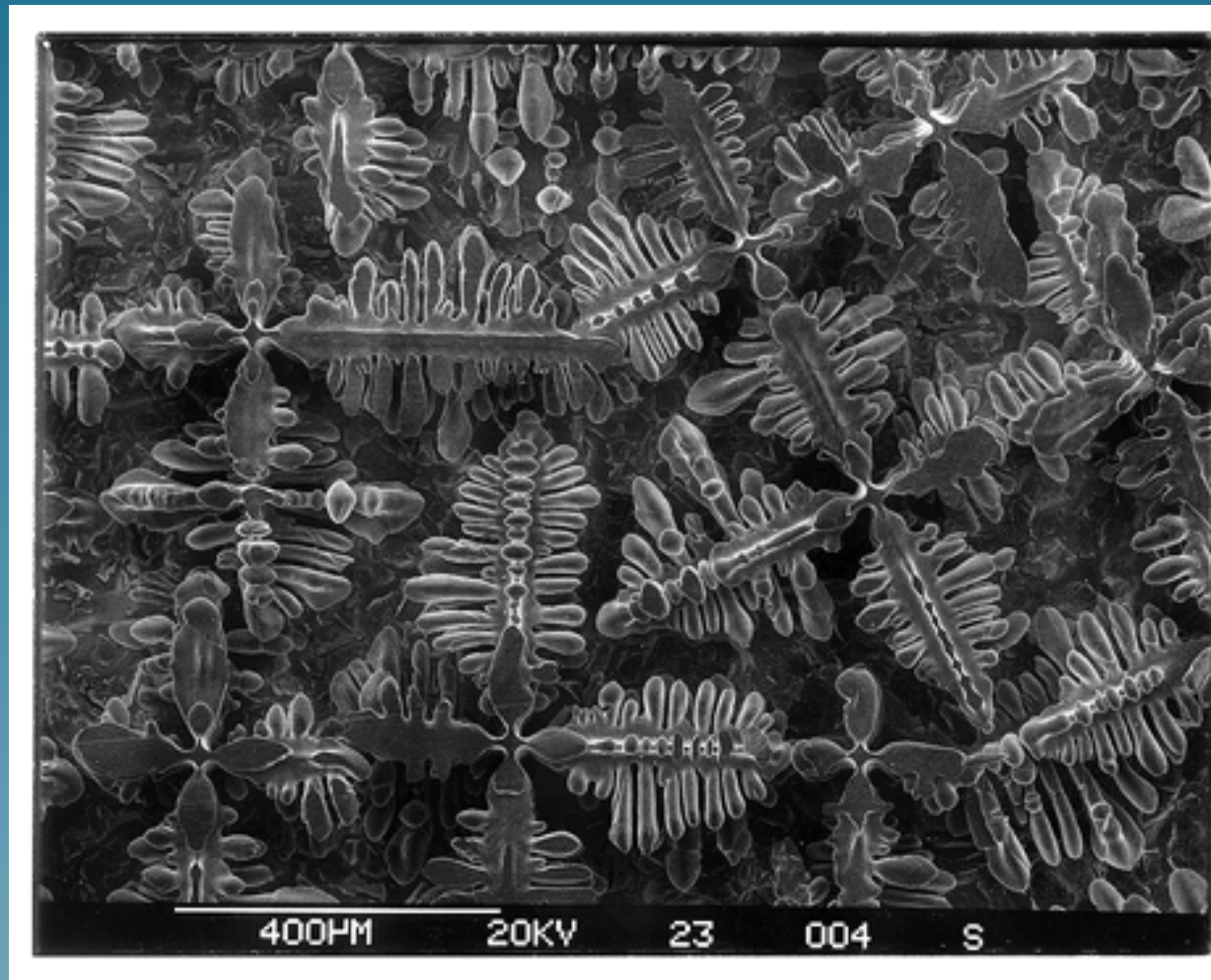
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Outline

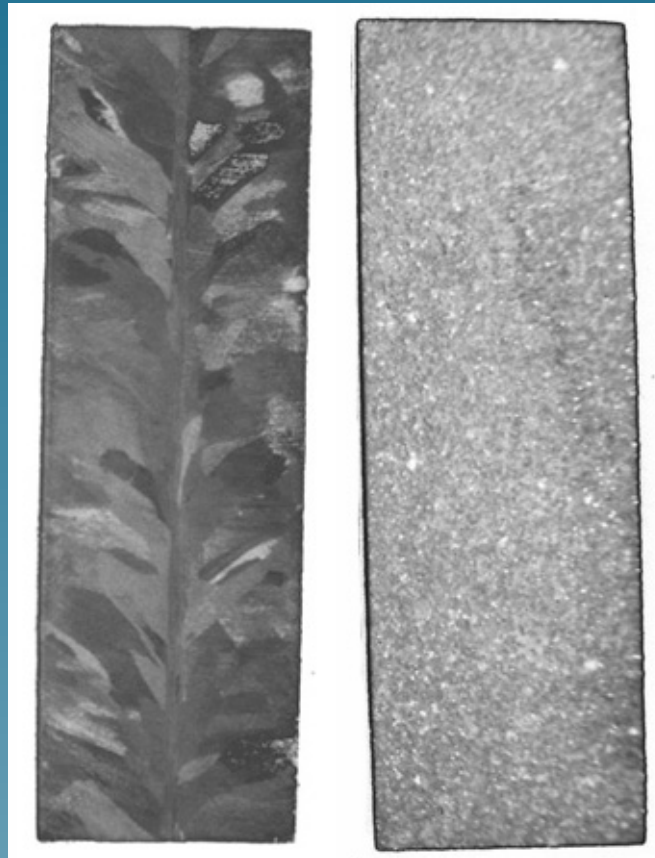
- A phase field model for dendritic growth of binary alloys
 - ★ Model
 - ★ Existence, a priori and a posteriori error estimates
 - ★ Numerical Tool : Adaptive finite elements with high aspect ratio
- A multiphase field model for the coalescence of binary alloys

Solidification : dendritic growth



Sa-Co alloy

Solidification : from macro to micro scale



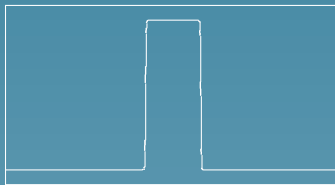
Grain shape and size (→ mechanical properties) :
depend on solidification history

A phase field model for dendritic growth of a binary alloy

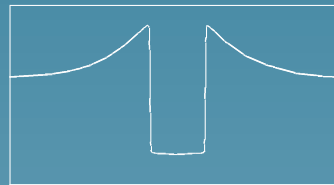
- Phase field model (Warren Boettinger Acta Metall. Mater. 1995, Taden Nestler Diepers Steinbach Phys D 1998). Find $c, \phi : \Omega \times (0, T) \rightarrow \mathbb{R}$ such that

$$\frac{\partial \phi}{\partial t} - \operatorname{div} (A(\nabla \phi) \nabla \phi) - S(c, \phi) = 0 \quad \text{in } \Omega \times (0, T),$$

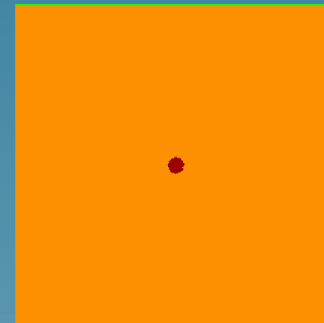
$$\frac{\partial c}{\partial t} - \operatorname{div} (D_1(\phi) \nabla c + D_2(c, \phi) \nabla \phi) = 0 \quad \text{in } \Omega \times (0, T).$$



Phase field ϕ
 $\phi = 0$: liquid
 $\phi = 1$: solid



Concentration c



Initial time



Final time

- interface width : ε small $\simeq 10^{-8}$ m (100 atoms).

The phase field equation

- Phase field

$$\frac{\partial \phi}{\partial t} - \operatorname{div} (A(\nabla \phi) \nabla \phi) - S(c, \phi) = 0.$$

- Free energy = interface (anisotropy) + double wells + phase transformation

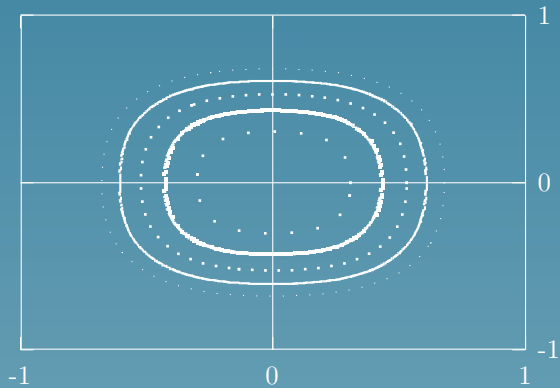
$$\frac{\varepsilon}{2} \int_{\Omega} a^2(\theta(\nabla \phi)) |\nabla \phi|^2 + \frac{1}{\varepsilon} \int_{\Omega} W(\phi) + \int_{\Omega} c_{\ell} - c_{\ell}^{eq},$$

with $a(\theta) = (1 + \bar{a} \cos(\kappa\theta))$ and $\theta(\nabla \phi)$ angle between $\nabla \phi$ and horizontal.

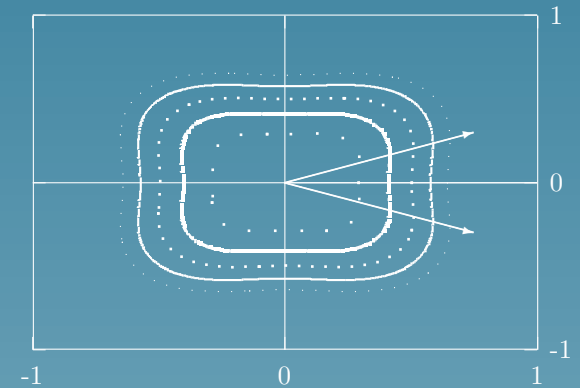
- Small parameter in $S(c, \phi)$ (time step $\simeq \varepsilon^2$, Elliott State of the art in numer. anal. 1997), strongly nonlinear $\operatorname{div} (A(\nabla \phi) \nabla \phi)$.
- Existence for low physical anisotropy $\bar{a} < \frac{1}{\kappa^2 - 1}$, a priori error estimates (Burman Rappaz M3AS 2003).
- A posteriori error estimates, adaptive FE with high aspect ratio (Burman Picasso J. Interfaces Free Boundaries 2003).

Small and large physical anisotropy

- Interface energy $\int_{\Omega} a^2(\theta(\nabla\phi)) |\nabla\phi|^2$.
- $a(\theta) = (1 + \bar{a} \cos(\kappa\theta))$ and $\theta(\nabla\phi)$ angle between $\nabla\phi$ and horizontal.
- isolines of $\xi \rightarrow a^2(\theta(\xi)) |\xi|^2$



Small physical anisotropy $\bar{a} < \frac{1}{\kappa^2 - 1}$



Large physical anisotropy $\bar{a} > \frac{1}{\kappa^2 - 1}$

A posteriori error estimates, adaptive FE with high aspect ratio

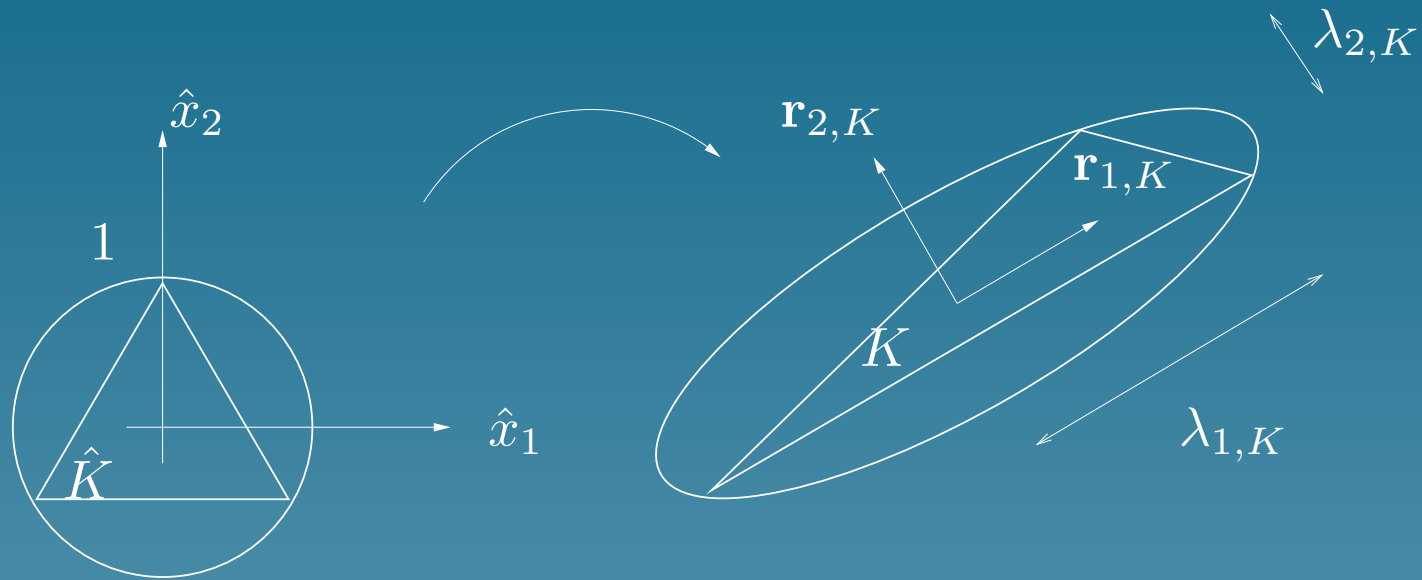
- A posteriori error estimates : $\text{error} \leq \text{estimator}(\text{mesh}, \text{numerical solution})$.
- $A(\cdot)$ is strongly elliptic : $\bar{a} < \frac{1}{\kappa^2 - 1}, \exists \mu$

$$\mu \int_{\Omega} |\nabla(\phi - \psi)|^2 \leq \int_{\Omega} \left(A(\nabla\phi)\nabla\phi - A(\nabla\psi)\nabla\psi \right) \cdot \nabla(\phi - \psi) \quad \forall \phi, \psi \in H_0^1(\Omega).$$

- The error in the $L^2(0, T; L^2(\Omega))$ norm converges faster to zero than the error in the $L^2(0, T; H^1(\Omega))$ norm.
- Then, $\exists C$ independent of “everything” (problem data, mesh size and aspect ratio) such that

$$\begin{aligned} \mu \int_0^T \int_{\Omega} |\nabla(\phi - \phi_h)|^2 + \frac{\mu D_1^2}{D_2^2} \int_0^T \int_{\Omega} |\nabla(c - c_h)|^2 \\ \leq C \left(\text{est}_{\phi}(\text{mesh}, \phi_h, c_h) + \frac{\mu D_1^2}{D_2^2} \text{est}_c(\text{mesh}, \phi_h, c_h) \right). \end{aligned}$$

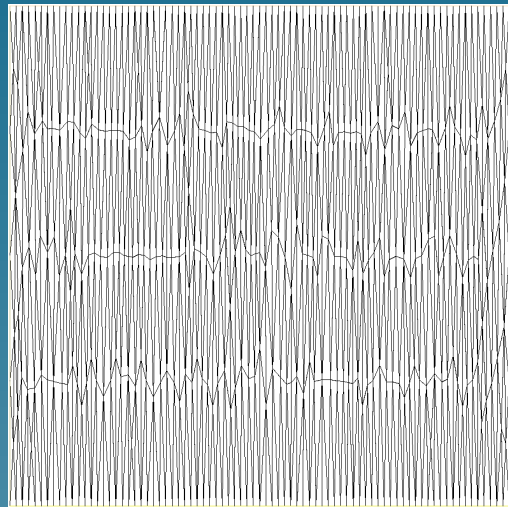
Error indicator for meshes with high aspect ratio



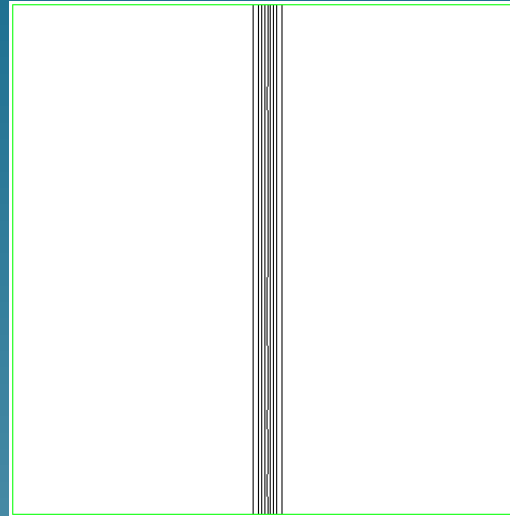
$$\frac{1}{2\lambda_{2,K}^{1/2}} \left\| \left[\frac{\partial c_h}{\partial n} \right] \right\|_{L^2(\partial K)} \left(\lambda_{1,K}^2 \left(\mathbf{r}_{1,K}^T G_K (c - c_h) \mathbf{r}_{1,K} \right) + \lambda_{2,K}^2 \left(\mathbf{r}_{2,K}^T G_K (c - c_h) \mathbf{r}_{2,K} \right) \right)^{1/2}$$

where $G_K(\cdot)$ is the matrix of first order derivatives, approached using post-processing techniques (Picasso SISC 2003).

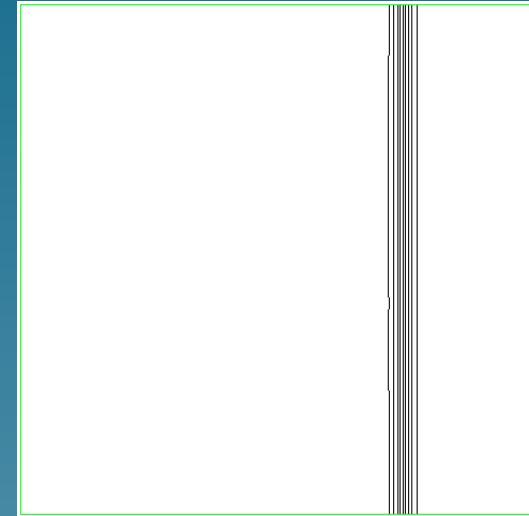
Numerical validation of the error indicator



mesh



ϕ, c at initial time



ϕ, c at final time

$h_1 - h_2$	e_{L^2}	e_{H^1}	ei^{ZZ}	ei^A
0.000005 – 0.0001	$1.1 \cdot 10^{-6}$	0.29	1.01	1.85
0.0000025 – 0.00005	$3.2 \cdot 10^{-7}$	0.13	1.01	1.74
0.00000125 – 0.000025	$8.8 \cdot 10^{-8}$	0.066	1.01	1.74

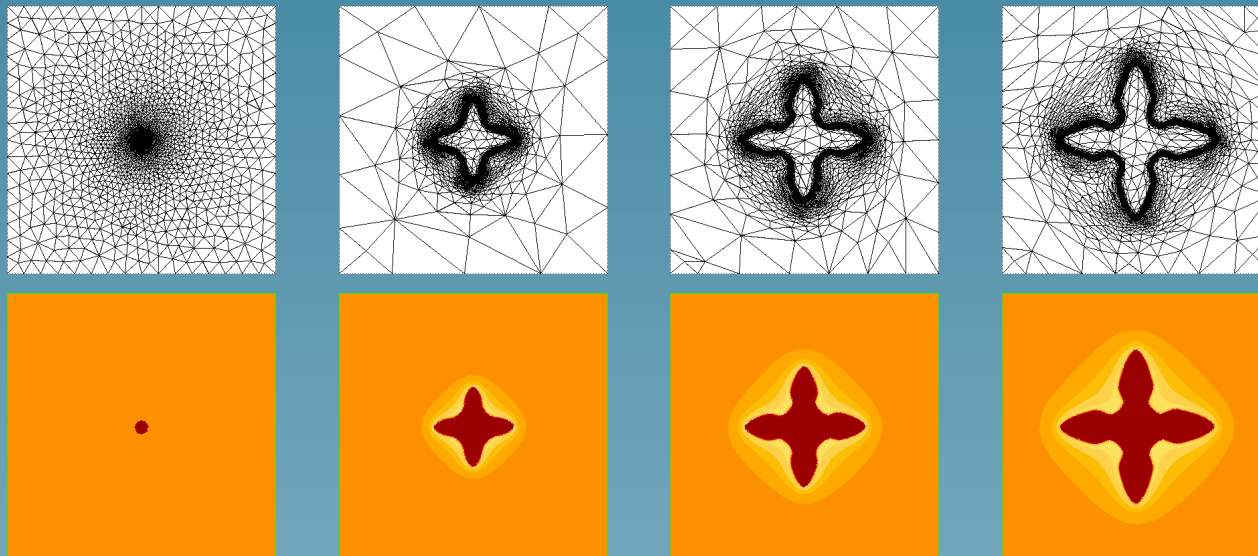
ei : effectivity index, error indicator / true error.

Small physical anisotropy

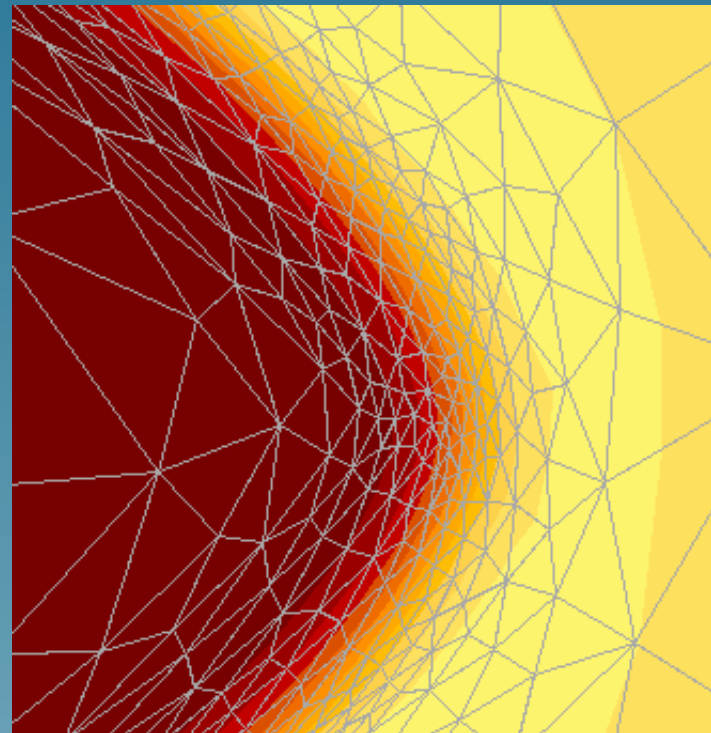
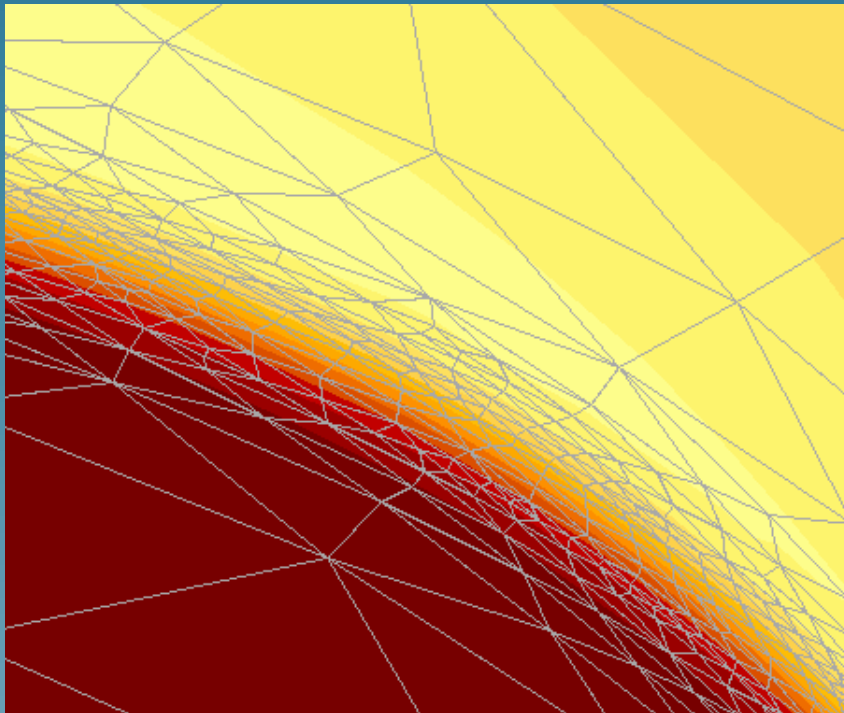
- Goal of the adaptive algorithm : build a sequence of triangulations such that

$$\frac{\text{error indicator}}{\int_0^T \int_{\Omega} |\nabla c_h|^2} \simeq TOL.$$

- Box width $5 \cdot 10^{-4}$, $\varepsilon = 5 \cdot 10^{-7}$, time step $5 \cdot 10^{-4}$, $TOL = 0.0625$, 24000 vertices, final time 1.



Small physical anisotropy



Same precision with isotropic meshes : 10 times more vertices !

Convergence



TOL=0.25
1987 Vertices



TOL=0.125
6073 Vertices

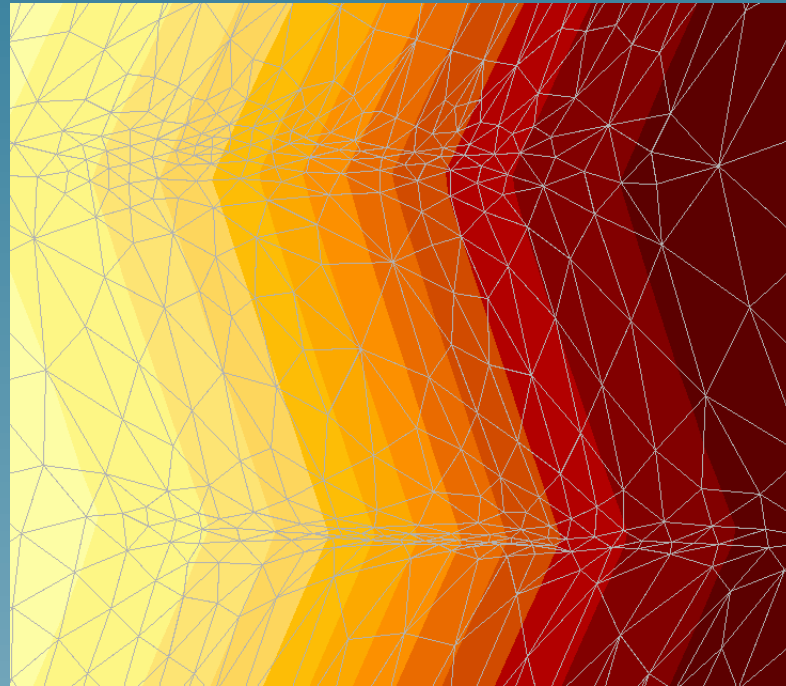
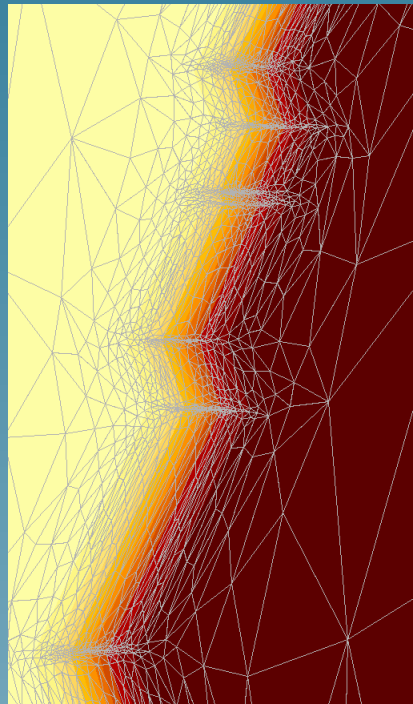
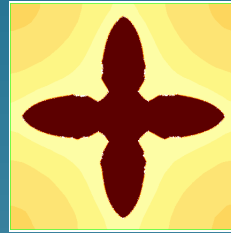


TOL=0.0625
24441 Vertices

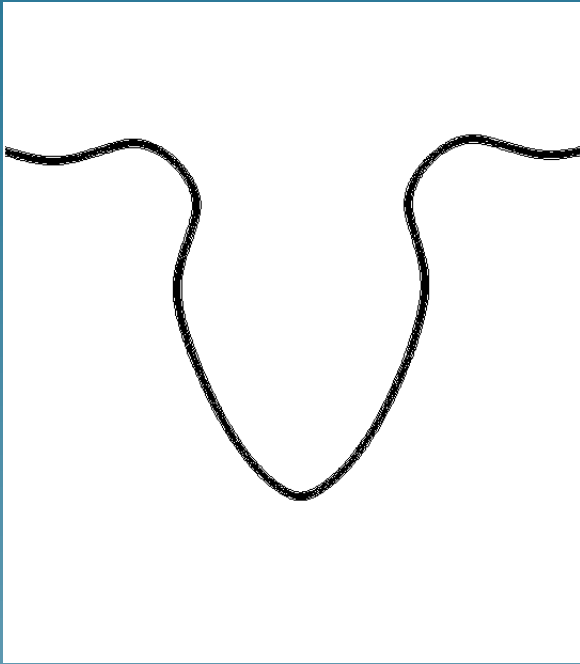


TOL=0.03125
101782 Vertices

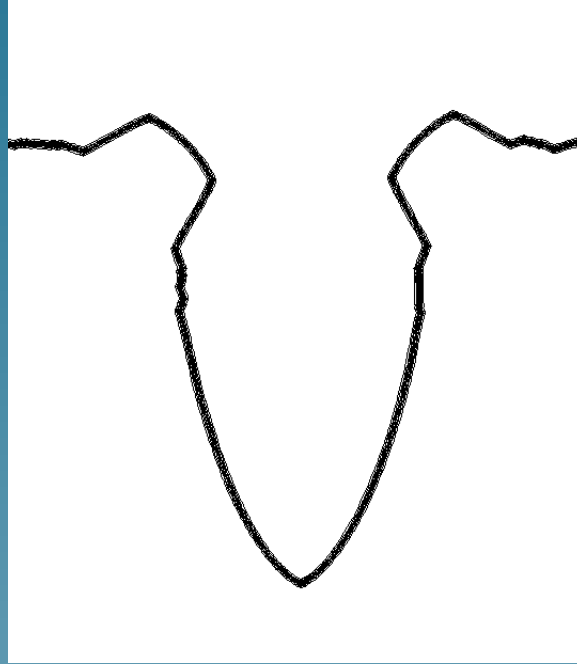
Large physical anisotropy



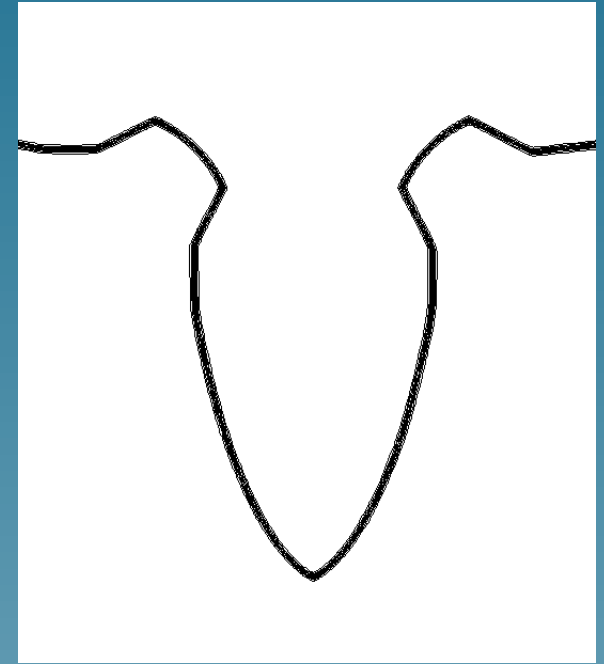
ϕ isolines according to physical anisotropy



Low anisotropy

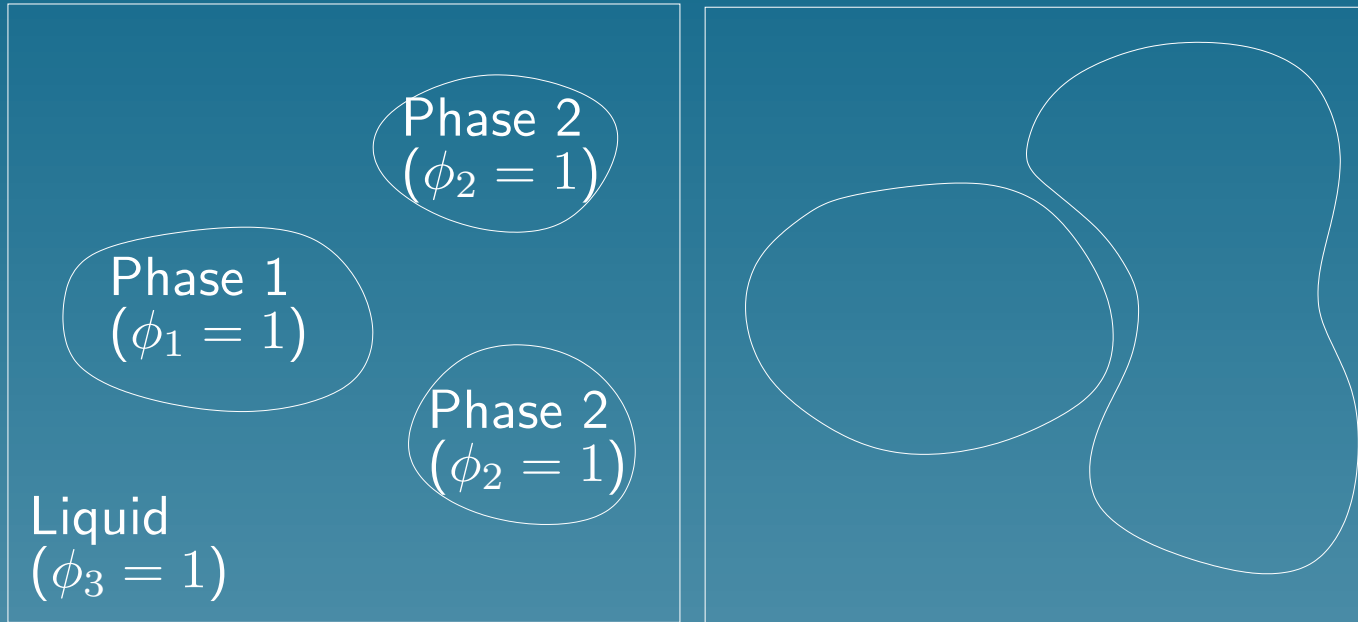


High anisotropy



High anisotropy
convexified functional

A multiphase field model for coalescence in binary alloys



- Multiphase field : Tiaden Nestler Diepers Steinbach Phys D 1998
- Multiphase field for binary alloys : Rappaz Jacot Boettinger Met. Trans. A 2003, Burman Jacot Picasso J. Comp. Phys. 2004
- Unknowns : $\phi_1, \phi_2, \phi_3, \lambda$ (Lagrange multiplier $\phi_1 + \phi_2 + \phi_3 = 1$) and c .

Free energy

- Interface energy

$$\begin{aligned}
 J_{int}(\phi_1, \phi_2, \phi_3) &= \frac{\varepsilon_{12}^2}{2} \int_{\Omega} a^2 \left(\theta_{12}(\mathbf{r}(\phi_1, \phi_2)) \right) |\mathbf{r}(\phi_1, \phi_2)|^2 \\
 &\quad + \frac{\varepsilon_{13}^2}{2} \int_{\Omega} a^2 \left(\theta_{13}(\mathbf{r}(\phi_1, \phi_3)) \right) |\mathbf{r}(\phi_1, \phi_3)|^2 \\
 &\quad + \frac{\varepsilon_{23}^2}{2} \int_{\Omega} a^2 \left(\theta_{23}(\mathbf{r}(\phi_2, \phi_3)) \right) |\mathbf{r}(\phi_2, \phi_3)|^2
 \end{aligned}$$

where $\mathbf{r}(\phi_i, \phi_j) = \phi_i \nabla \phi_j - \phi_j \nabla \phi_i$ $(i, j) \in \{(1, 2), (1, 3), (2, 3)\}$

- Phase transformation $J_{tr}(\phi_1, \phi_2, \phi_3) = \int_{\Omega} (c_{\ell} - c_{\ell}^{eq})$
- Double wells $J_{dw}(\phi_1, \phi_2, \phi_3) = \frac{1}{\varepsilon} \int_{\Omega} \phi_1^2 \phi_2^2 + \phi_1^2 \phi_3^2 + \phi_2^2 \phi_3^2$

The parabolic system of equations

- Find ϕ_1, ϕ_2, ϕ_3 such that $J_{int} + J_{tr} + J_{dw} = \min$ and $\phi_1 + \phi_2 + \phi_3 = 1$
- Lagrangian

$$\mathcal{L}(\phi_1, \phi_2, \phi_3, \lambda) = (J_{int} + J_{tr} + J_{dw})(\phi_1, \phi_2, \phi_3) + \int_{\Omega} \lambda(\phi_1 + \phi_2 + \phi_3 - 1).$$

- $\mathcal{D}\mathcal{L}(\phi_1, \phi_2, \phi_3, \lambda) = 0$
- Find $\phi_1, \phi_2, \phi_3, \lambda$ such that

$$\frac{\partial \phi_1}{\partial t} + \mathcal{D}_{\phi_1} \mathcal{L}(\phi_1, \phi_2, \phi_3, \lambda) = 0,$$

$$\frac{\partial \phi_2}{\partial t} + \mathcal{D}_{\phi_2} \mathcal{L}(\phi_1, \phi_2, \phi_3, \lambda) = 0,$$

$$\frac{\partial \phi_3}{\partial t} + \mathcal{D}_{\phi_3} \mathcal{L}(\phi_1, \phi_2, \phi_3, \lambda) = 0,$$

$$\phi_1 + \phi_2 + \phi_3 - 1 = 0.$$

The parabolic system of equations

- Weak formulation with no anisotropy

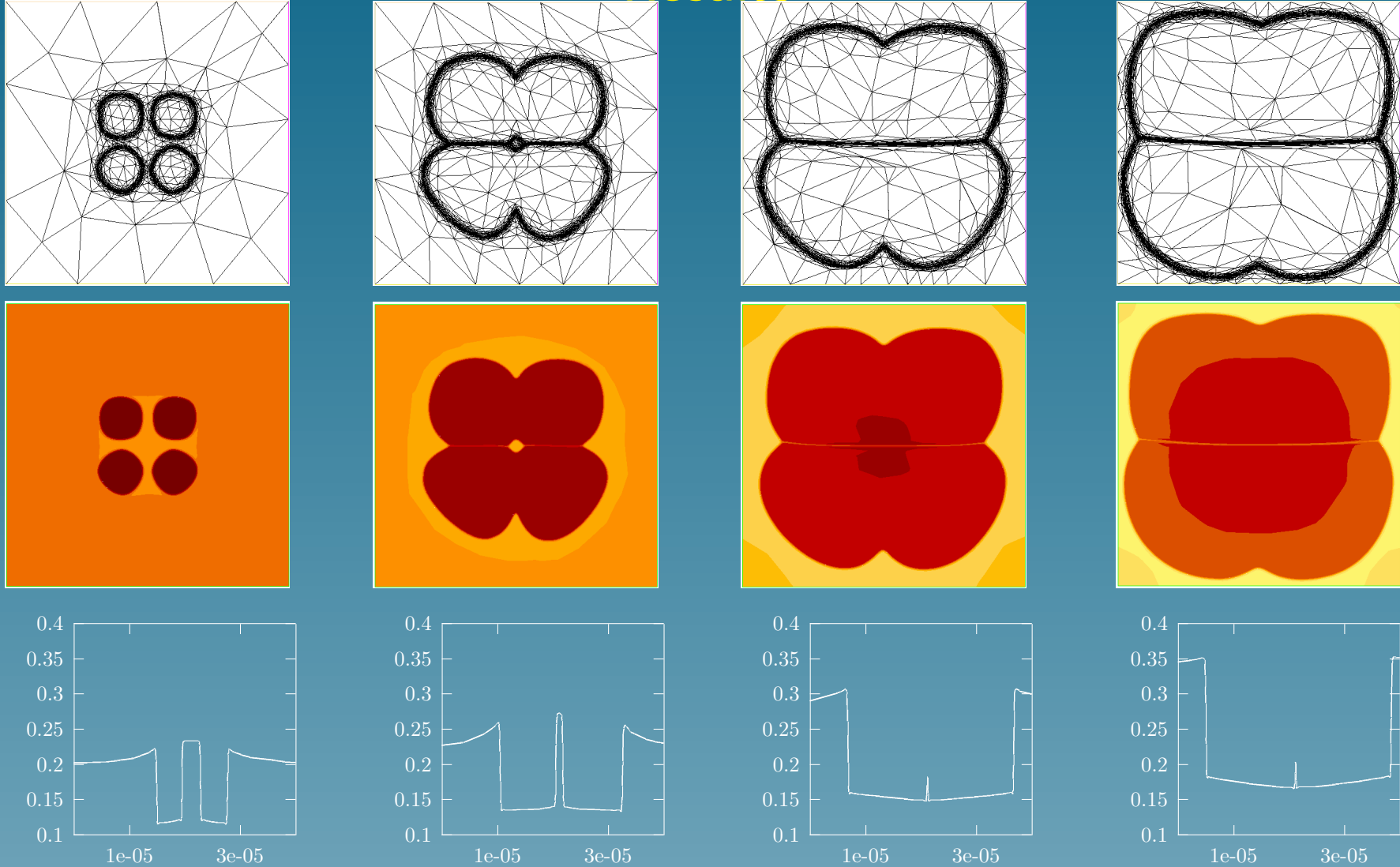
$$\begin{aligned}
 \int_{\Omega} & \left(\begin{pmatrix} \frac{\partial \phi_1}{\partial t} \\ \frac{\partial \phi_2}{\partial t} \\ \frac{\partial \phi_3}{\partial t} \end{pmatrix} \cdot \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix} + \begin{pmatrix} (\phi_2^2 + \phi_3^2)I_2 & -\phi_1\phi_2I_2 & -\phi_1\phi_3I_2 \\ \dots & \dots & \dots \\ \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} \nabla \phi_1 \\ \nabla \phi_2 \\ \nabla \phi_3 \end{pmatrix} \cdot \begin{pmatrix} \nabla \psi_1 \\ \nabla \psi_2 \\ \nabla \psi_3 \end{pmatrix} \right. \\
 & + \begin{pmatrix} |\nabla \phi_2|^2 + |\nabla \phi_3|^2 & -\nabla \phi_1 \cdot \nabla \phi_2 & -\nabla \phi_1 \cdot \nabla \phi_3 \\ \dots & \dots & \dots \\ \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \end{pmatrix} \cdot \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix} \\
 & \left. + \text{double well stuff} + \lambda(\psi_1 + \psi_2 + \psi_3) \right) = 0,
 \end{aligned}$$

for all ψ_1, ψ_2, ψ_3 .

$$\int_{\Omega} (\phi_1 + \phi_2 + \phi_3) \mu = \int_{\Omega} \mu,$$

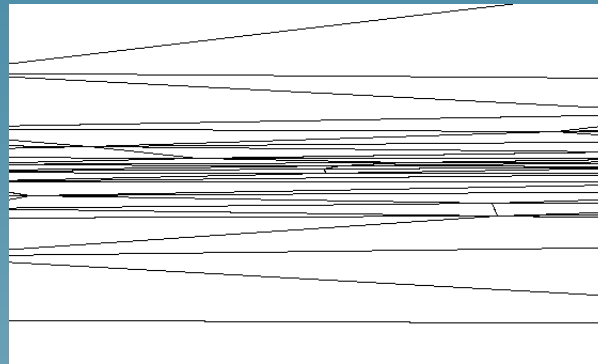
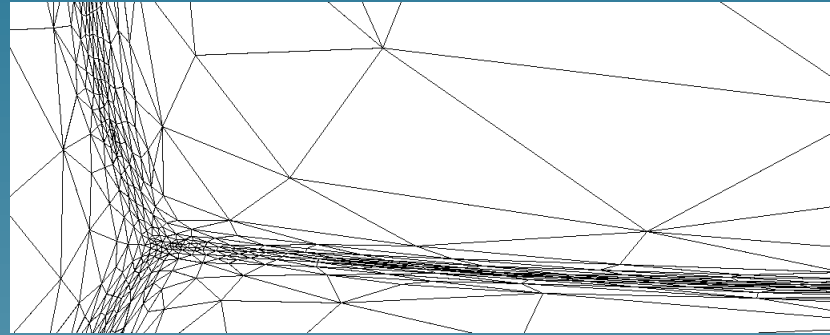
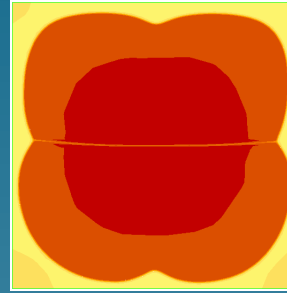
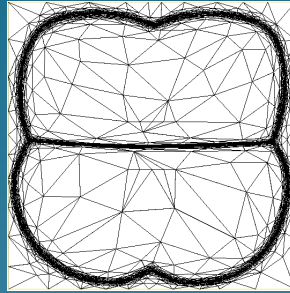
for all μ .

Results

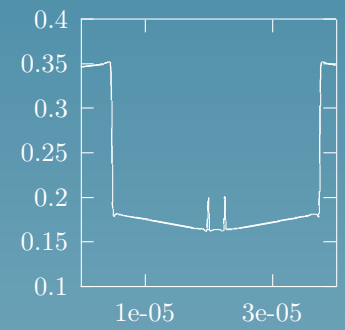
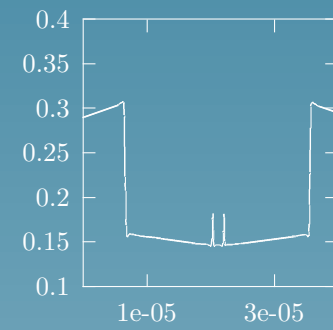
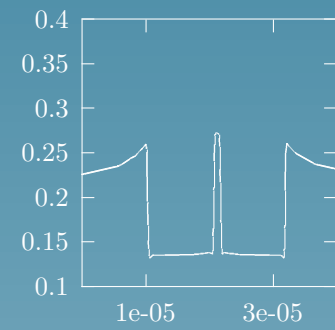
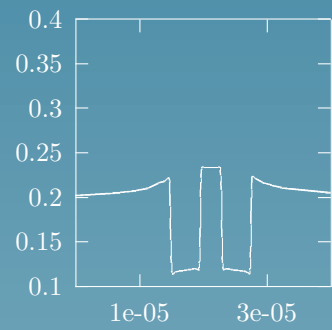
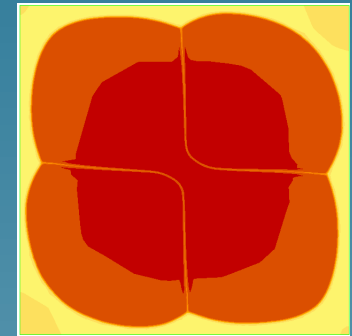
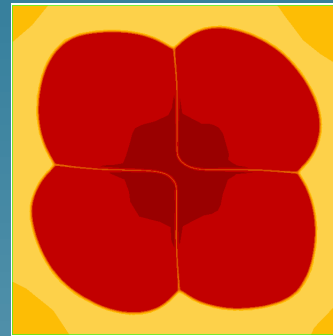
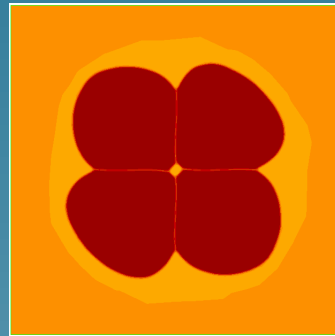
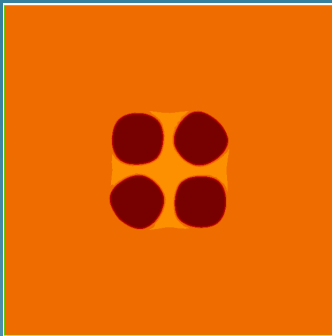
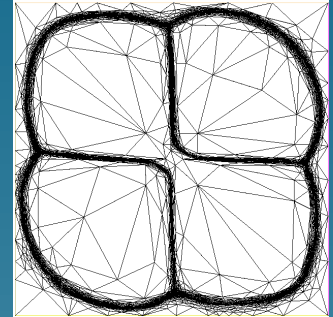
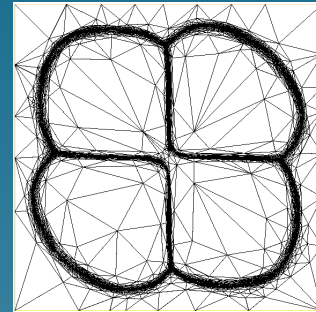
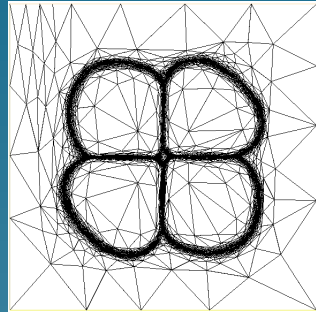
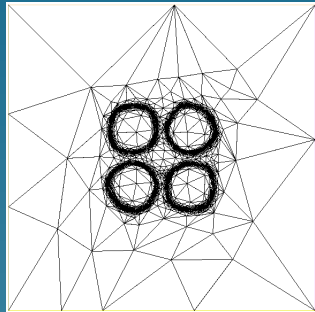


Box $3 \cdot 10^{-5}$, $\varepsilon = 5 \cdot 10^{-8}$, time step 10^{-3} , $TOL = 0.25$, 3000 vertices time 2.

Results



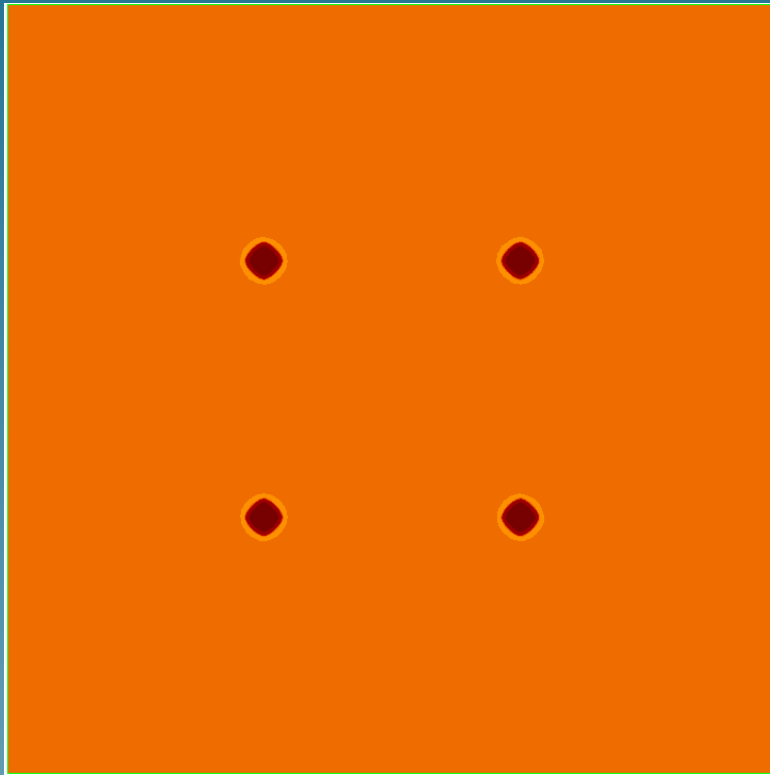
Results



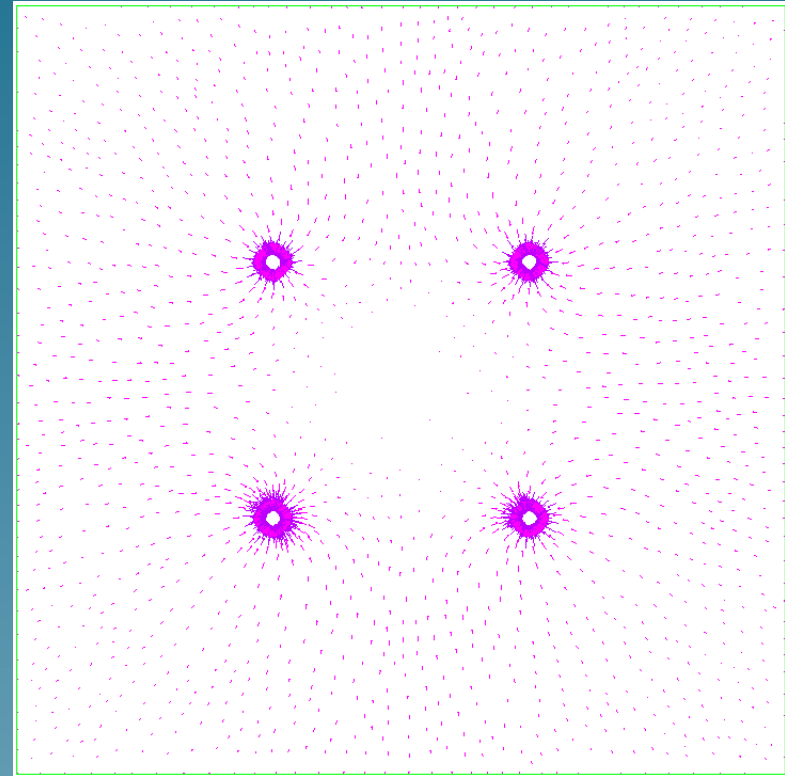
Conclusions and perspectives

- Dendritic growth and coalescence : adaptive finite elements with high aspect ratio → accurate results with few vertices ($< 20\ 000$).
- Mathematical analysis of coalescence.
- Dendritic growth and coalescence with convection.
- 3D ?

Dendritic growth and coalescence with convection

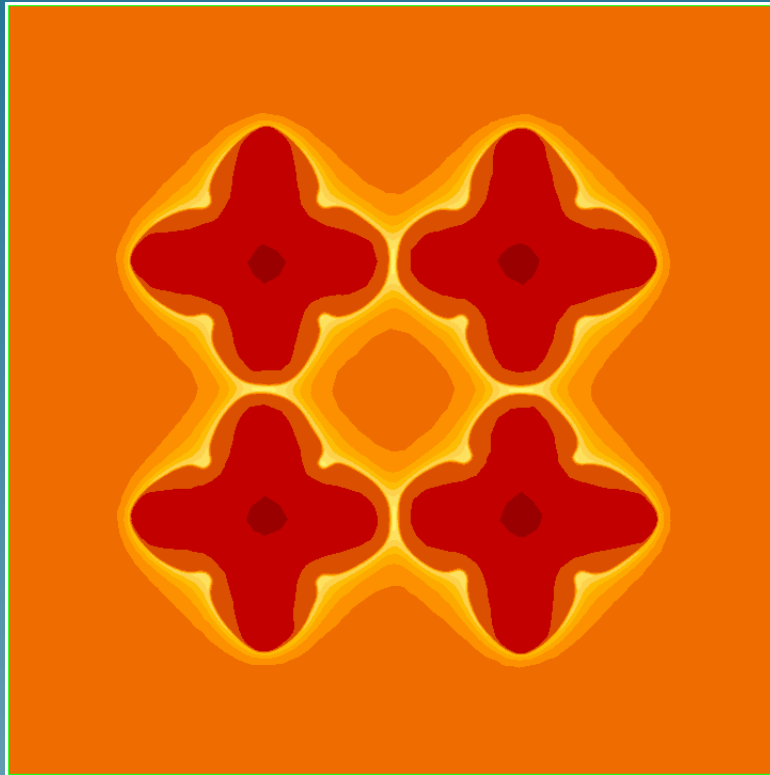


Concentration

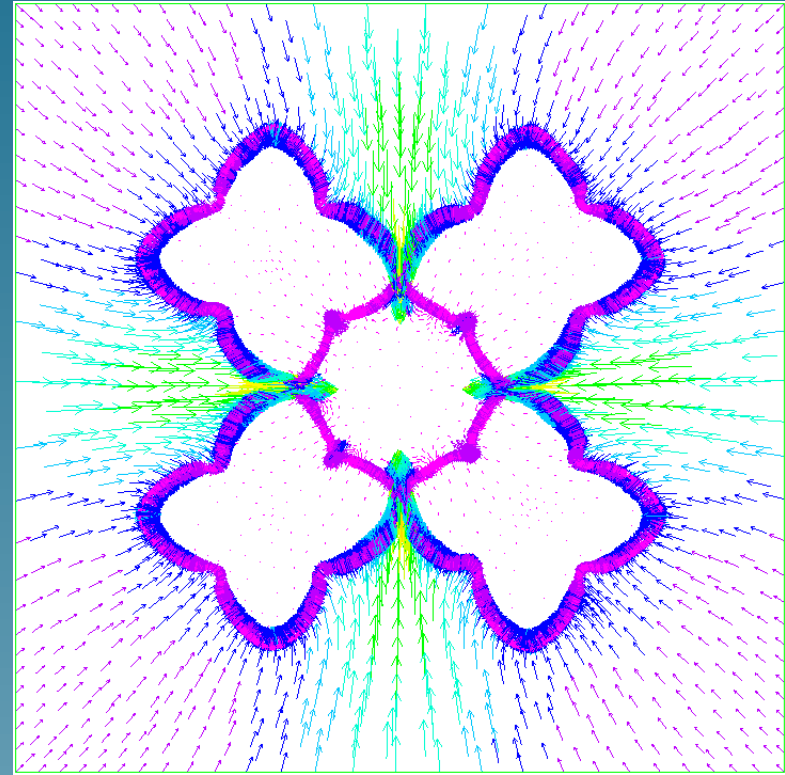


Velocity

Dendritic growth and coalescence with convection



Concentration



Velocity